

Joint Learning of Vessel Segmentation and Artery/Vein Classification with Post-processing

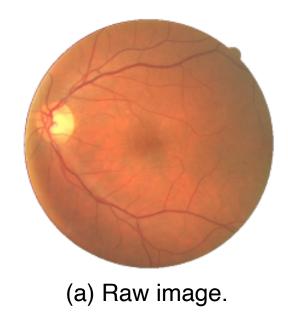
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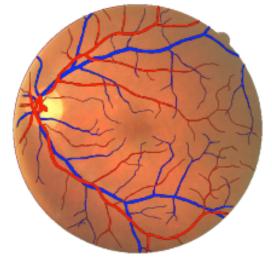
Background



- Retinal imaging is the only feasible way to directly inspect the vessels in the human body.
- Retinal segmentation and classification are important to help diagnosis of diabetes, hypertension, arterial hardening, etc.







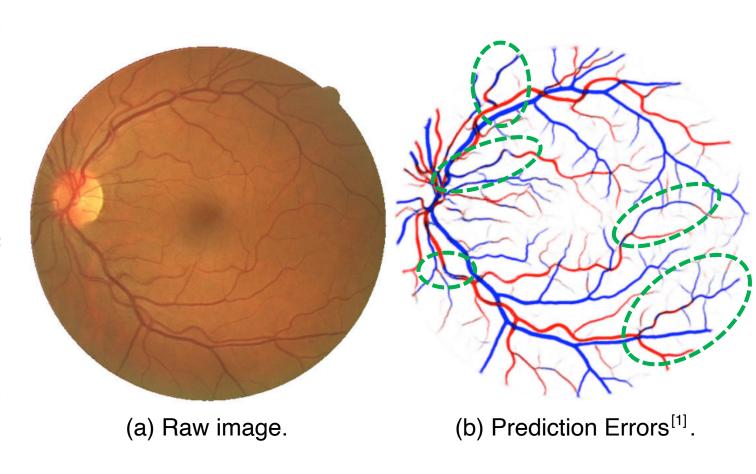
(b) Vessel segmentation.

(c) Artery/Vein classification.

Problems



- Retina images are usually complicated and full of noises.
- The available training data are very limited.
 - In most of the public datasets, the number of retina images for training is no more than 20.
- Vessel classification is more difficult because of the data unbalance.

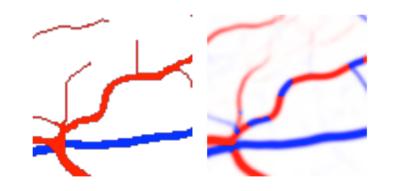


[1] Galdran, A., Meyer, M., Costa, P., & Campilho, A. (2019, April). Uncertainty-aware artery/vein classification on retinal images. In 2019 IEEE 16th International Symposium on Biomedical Imaging (ISBI 2019) (pp. 556-560). IEEE.

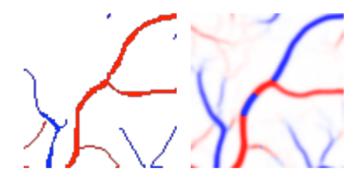
Our Solution



 UNet-like models depend more on local cues, such as color and contrast, rather than the structure of the whole vessel system.



Errors happen along vessel segments



Errors happen around crossing or branching points

- Therefore, we design our method with two components.
 - A neural model that segments and classifies vessels.
 - A post-processing algorithm to refine initial classification results.

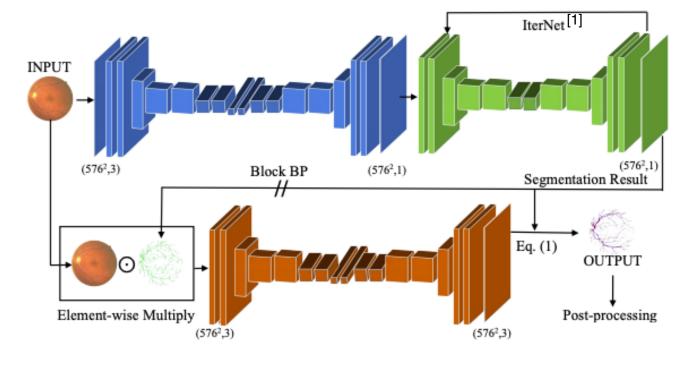
SeqNet Model



 Two streams for segmentation and classification.

 Element-wise multiplication with the segmentation results to simplify the classification task.

 Two results are merged to obtain accurate vessel map.

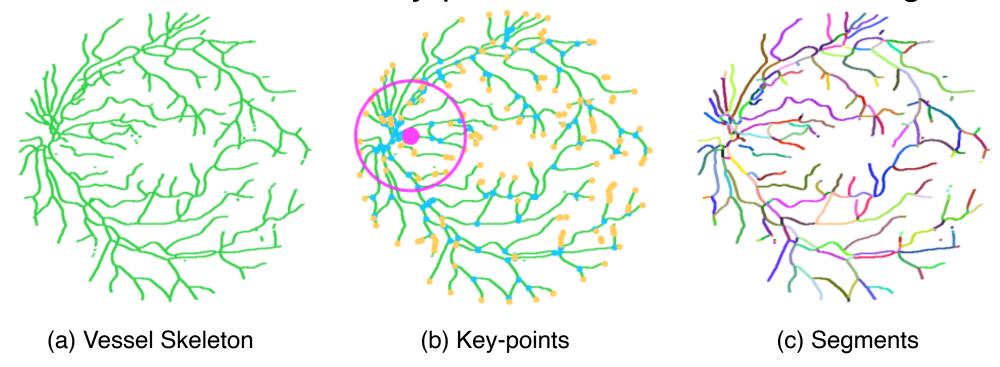


[1] Li, L., Verma, M., Nakashima, Y., Nagahara, H., & Kawasaki, R. (2020). Iternet: Retinal image segmentation utilizing structural redundancy in vessel networks. In *The IEEE Winter Conference on Applications of Computer Vision* (pp. 3656-3665).

Post-processing (Vessel Map Analysis)



- Key-points include the crossing points and the end points.
 - Crossing points are pixels with more than two neighbors, while terminal points only have no more than one neighbor.
- Pixels between connected key-points are extracted as a segment.

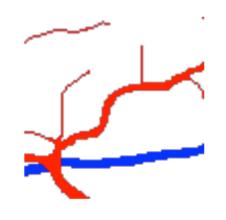


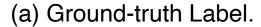
Post-processing (Intra-segment)

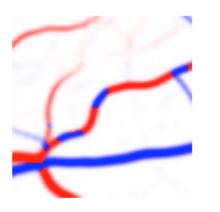


- A common prediction error is the inconsistency along one segment.
- We constraint pixels in each segment can only have one single label.
- Its category is given by the sum of each pixel's confidence.

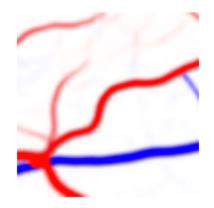
$$c_{li} = \sum_{k \in S_i} (o_{artery,k} - o_{vein,k})$$







(b) Prediction Error.

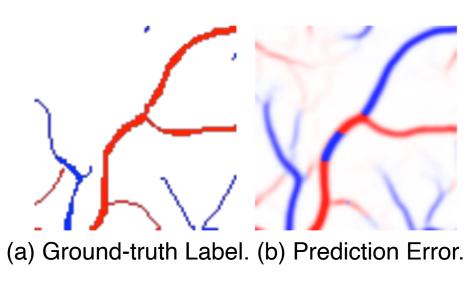


(c) Post-processed Result.

Post-processing (Inter-segment)



- Another kind of error usually happens around crossing and branching points.
- An observation is that classification failures come with low confidences.
- They may be corrected by their connecting.
- We introduced the inter-segment prediction propagation, in which the label of a segment is propagated to its connected segments.



Run 3
Run 4

Experimental Results



- The proposed method achieves higher AUC, as our model avoids deterioration of the segmentation performance.
- · Also, it shows higher classification accuracy on both datasets.

Table 1: Performance evaluation on DRIVE dataset.

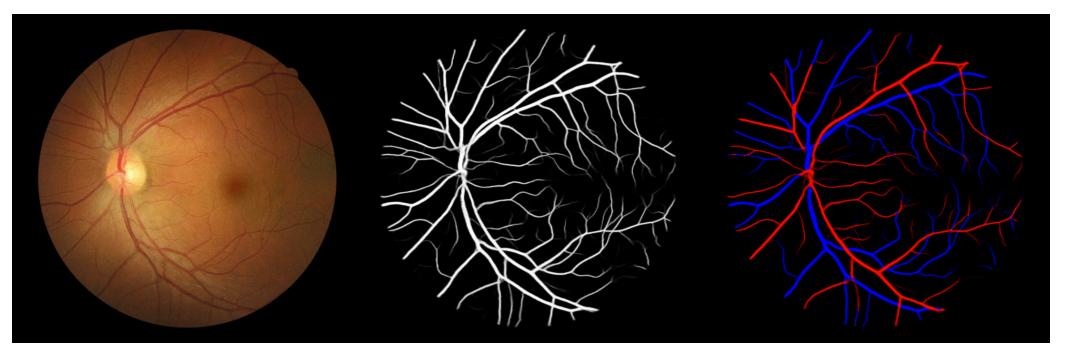
Methods	Full Image	Center		$Center_{\geq 2px}$		Vessel
		Acc.	F1	Acc.	F1	Vessei
UA (Galdran et al., 2019)	0.966	0.888	0.888	0.923	0.923	0.741
FCN (Hemelings et al., 2019)	-	-	-	0.940	-	-
SeqNet $w.o.$ post-processing	0.967	0.914	0.914	0.946	0.946	0.774
SeqNet w. post-processing	0.967	0.919	0.919	0.953	0.953	0.778

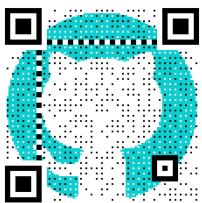
Table 2: Performance evaluation on LES-AV dataset.

Methods	Full Image	Center		$Center_{\geq 2 px}$		Vessel
		Acc.	F1	Acc.	F1	vesser
SeqNet $w.o.$ post-processing	0.978	0.858	0.858	0.916	0.916	0.776
SeqNet w. post-processing	0.978	0.874	0.874	0.930	0.930	0.785

Works well on other datasets (no FT)







Paper: https://arxiv.org/abs/2005.13337

Code: https://github.com/conscienceli/SeqNet

(Pretrained weights available)

