

# Differentiable Mutual Information and Matrix Exponential for Multi-Resolution Image Registration

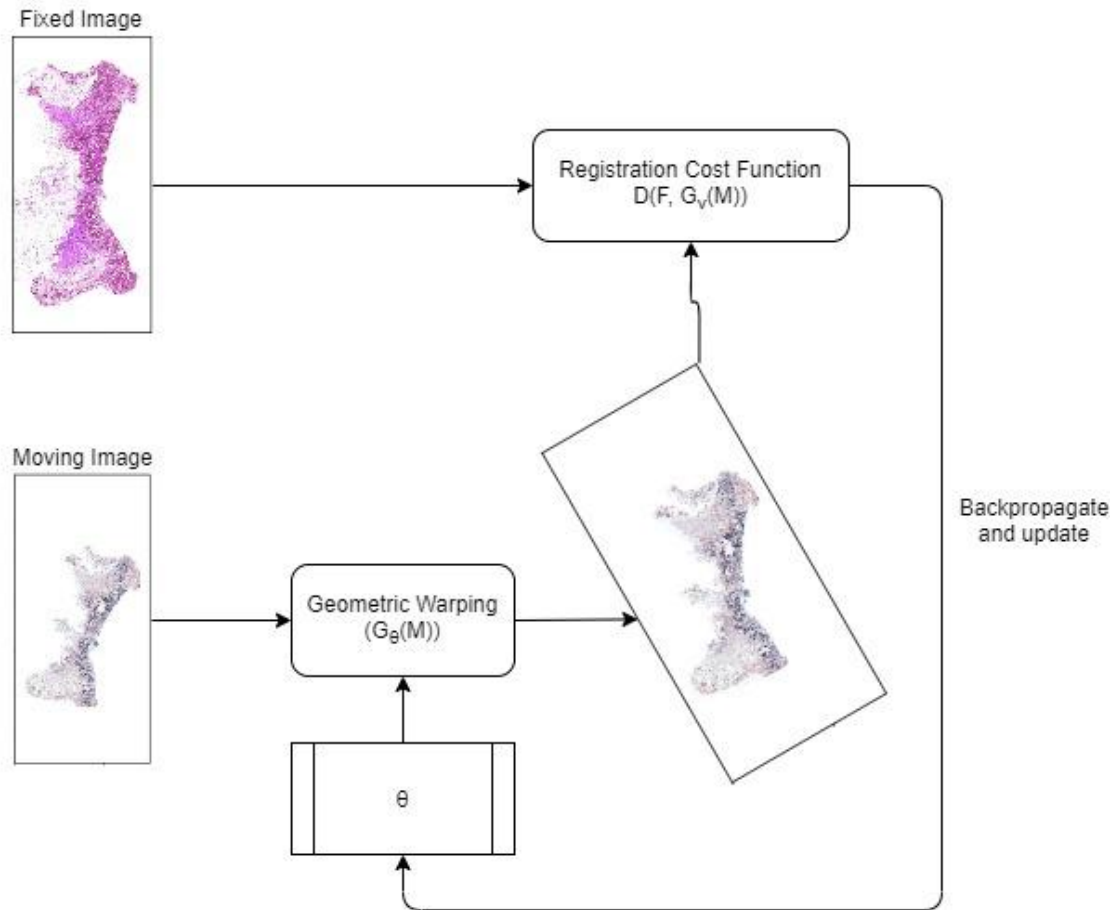
Abhishek Nan, Matthew Tennant, Uriel Rubin, Nilanjan  
Ray

Medical Imaging with Deep Learning, 2020

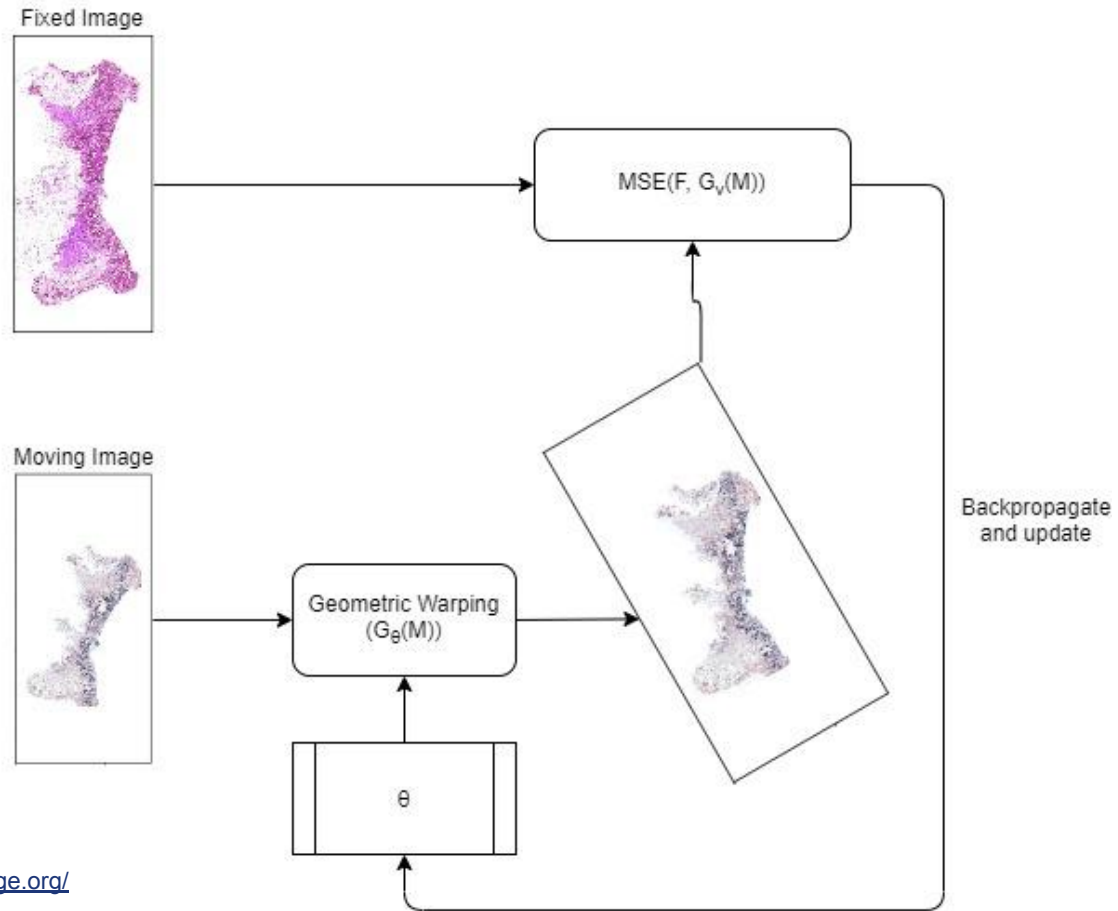
<https://github.com/abnan/DRMIME>



# Registration



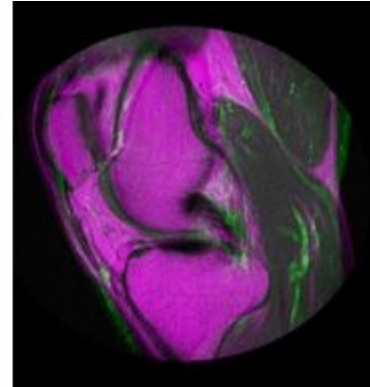
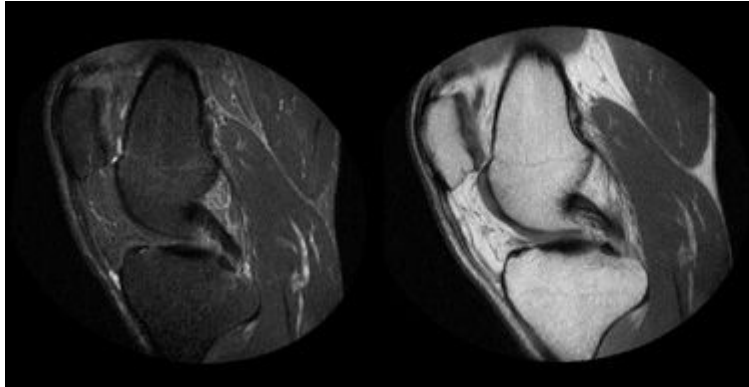
# With MSE





# Problems?

- Multi-modal images
- MSE won't work





# Solution?

- Mutual Information

$$MI(X, Y) = \sum_{x, y} p(x, y) \log \frac{p(x, y)}{p(x)p(y)}.$$



# Issues?

- Mutual Information for images is computed using joint histograms.
- Histograms are not differentiable.
- No gradient descent?



# Differentiable mutual information

- The function  $T$  is realized by a neural network with parameter  $\theta$ .
- $V(\theta)$  is differentiable and can be used as a objective function in place of MI.

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**Algorithm 1** MINE

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$\theta \leftarrow$  initialize network parameters

**repeat**

Draw  $b$  minibatch samples from the joint distribution:  
 $(\mathbf{x}^{(1)}, \mathbf{z}^{(1)}), \dots, (\mathbf{x}^{(b)}, \mathbf{z}^{(b)}) \sim \mathbb{P}_{XZ}$

Draw  $n$  samples from the  $Z$  marginal distribution:  
 $\bar{\mathbf{z}}^{(1)}, \dots, \bar{\mathbf{z}}^{(b)} \sim \mathbb{P}_Z$

Evaluate the lower-bound:

$$V(\theta) \leftarrow \frac{1}{b} \sum_{i=1}^b T_{\theta}(\mathbf{x}^{(i)}, \mathbf{z}^{(i)}) - \log\left(\frac{1}{b} \sum_{i=1}^b e^{T_{\theta}(\mathbf{x}^{(i)}, \bar{\mathbf{z}}^{(i)})}\right)$$

Evaluate bias corrected gradients (e.g., moving average):

$$\hat{G}(\theta) \leftarrow \tilde{\nabla}_{\theta} V(\theta)$$

Update the statistics network parameters:

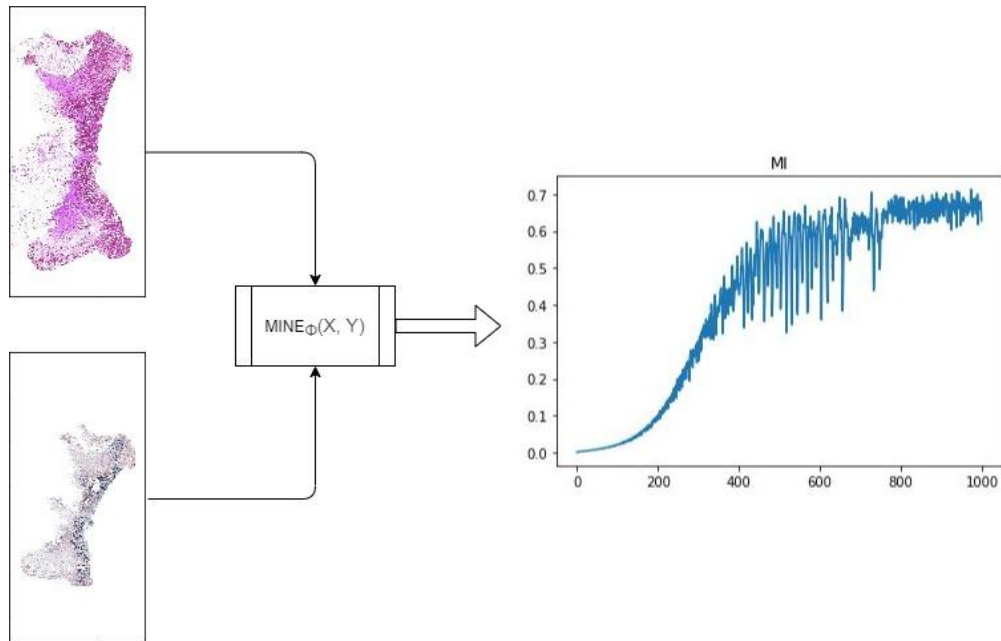
$$\theta \leftarrow \theta + \hat{G}(\theta)$$

**until** convergence

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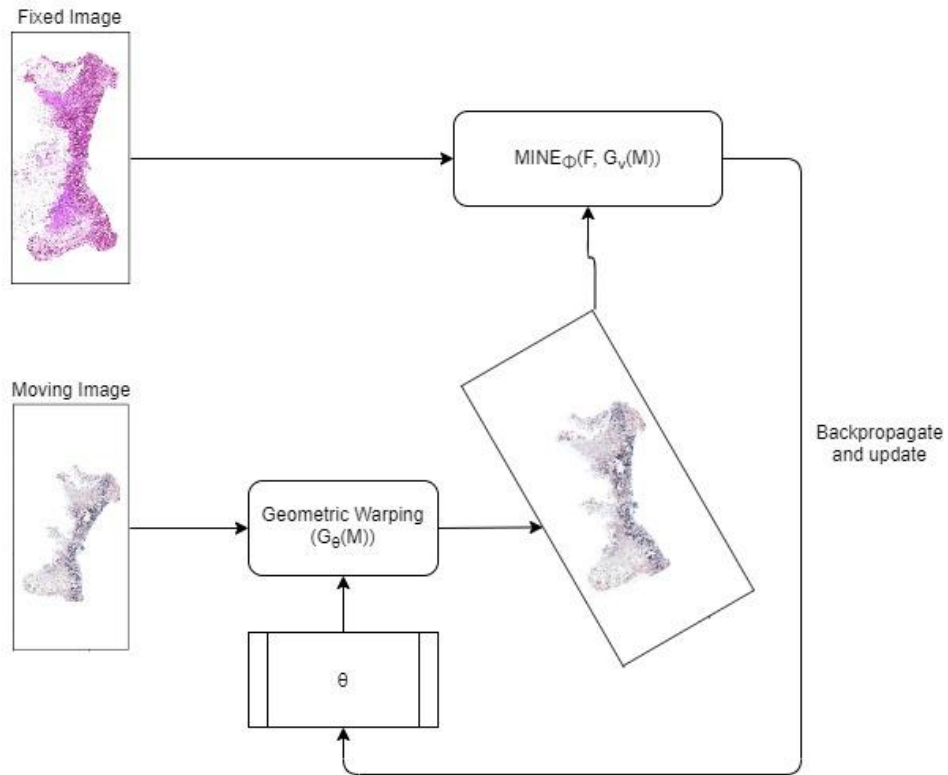


# MINE for images





# Currently





# Matrix exponential

- Matrix exponential of a square matrix  $A$  is given by the following:

$$\exp(A) = \sum_{k=0}^{\infty} \frac{A^k}{k!}$$

- Geometric transformation matrices can be obtained by exponential of a linear combination of basis matrices.



# Matrix Exponential (Examples)

- Affine transform

- Basis matrices:

$$B_1 = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, B_2 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}, B_3 = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, B_4 = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, B_5 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix}, B_6 = \begin{bmatrix} 0 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

- Transformation matrix:

$$\exp\left(\sum_{i=1}^6 \theta_i B_i\right) = \sum_{k=0}^{\infty} \frac{[\sum_{i=1}^6 \theta_i B_i]^k}{k!}$$



# Why matrix exponentials?

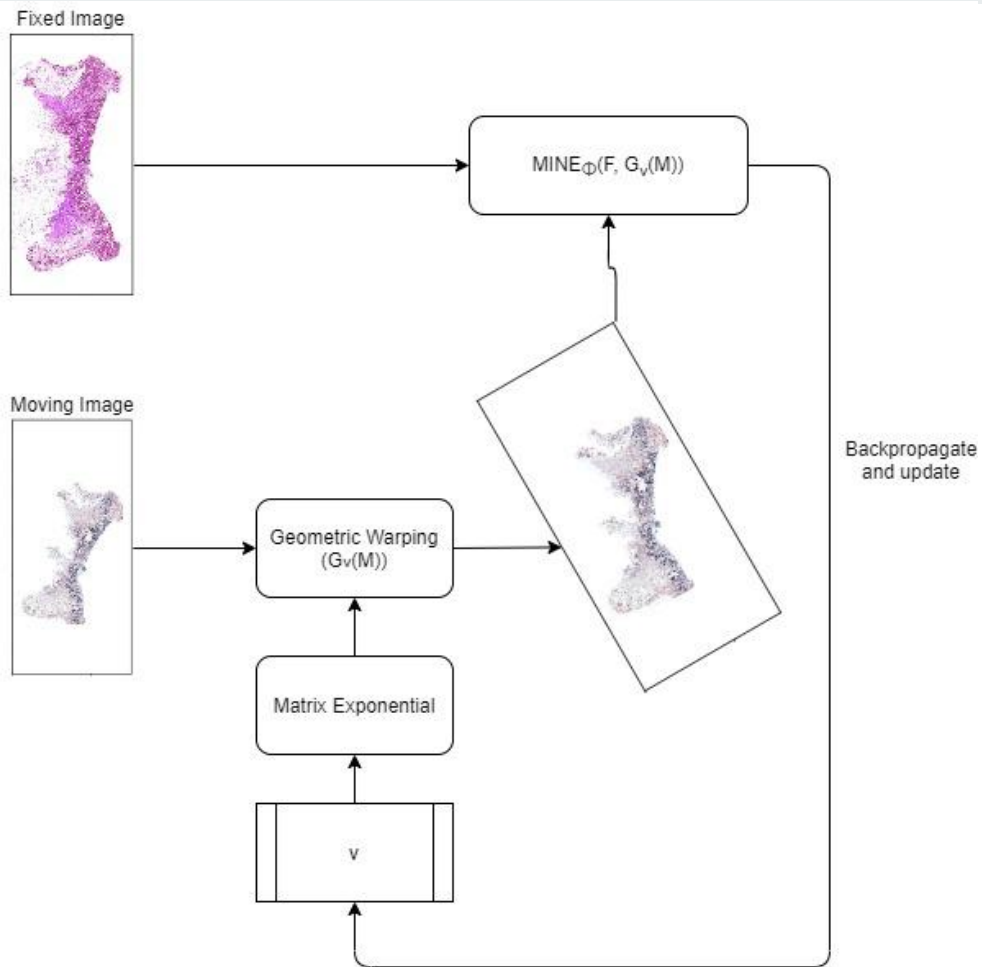
- Consider gradient descent on rotation matrix with these two options:
  - Option 1: Update each element of rotation matrix:

$$\begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix} \leftarrow \delta \begin{bmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{bmatrix}$$

- Option 2: Update parameter and use matrix exponential (use closed form expression here) when necessary

$$\theta \leftarrow \delta\theta$$

So far...





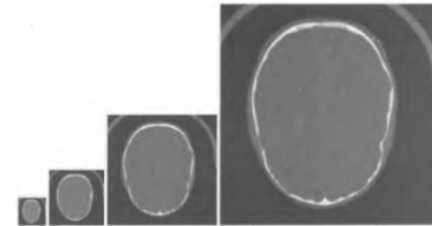
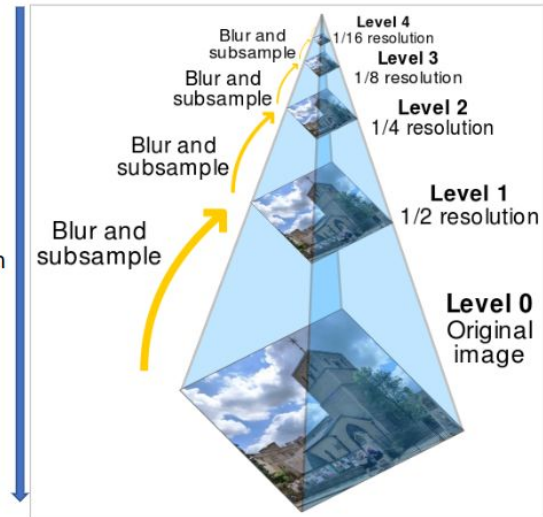
## More problems?

- Medical/Microscopy images often are extremely high resolution. So gradient descent can be extremely slow.
- Optimization for neural networks is non-convex.

# Solution?

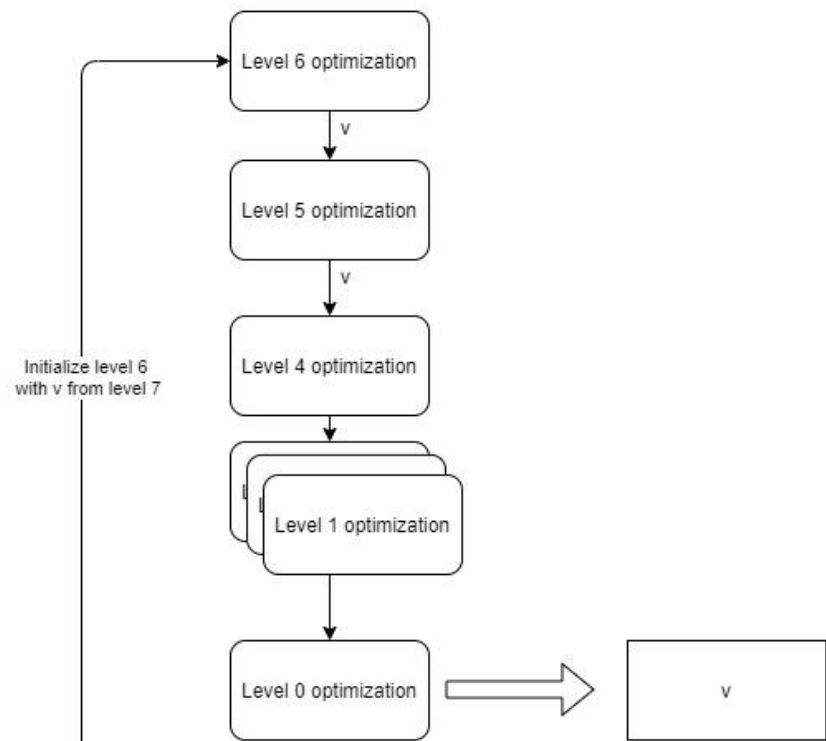
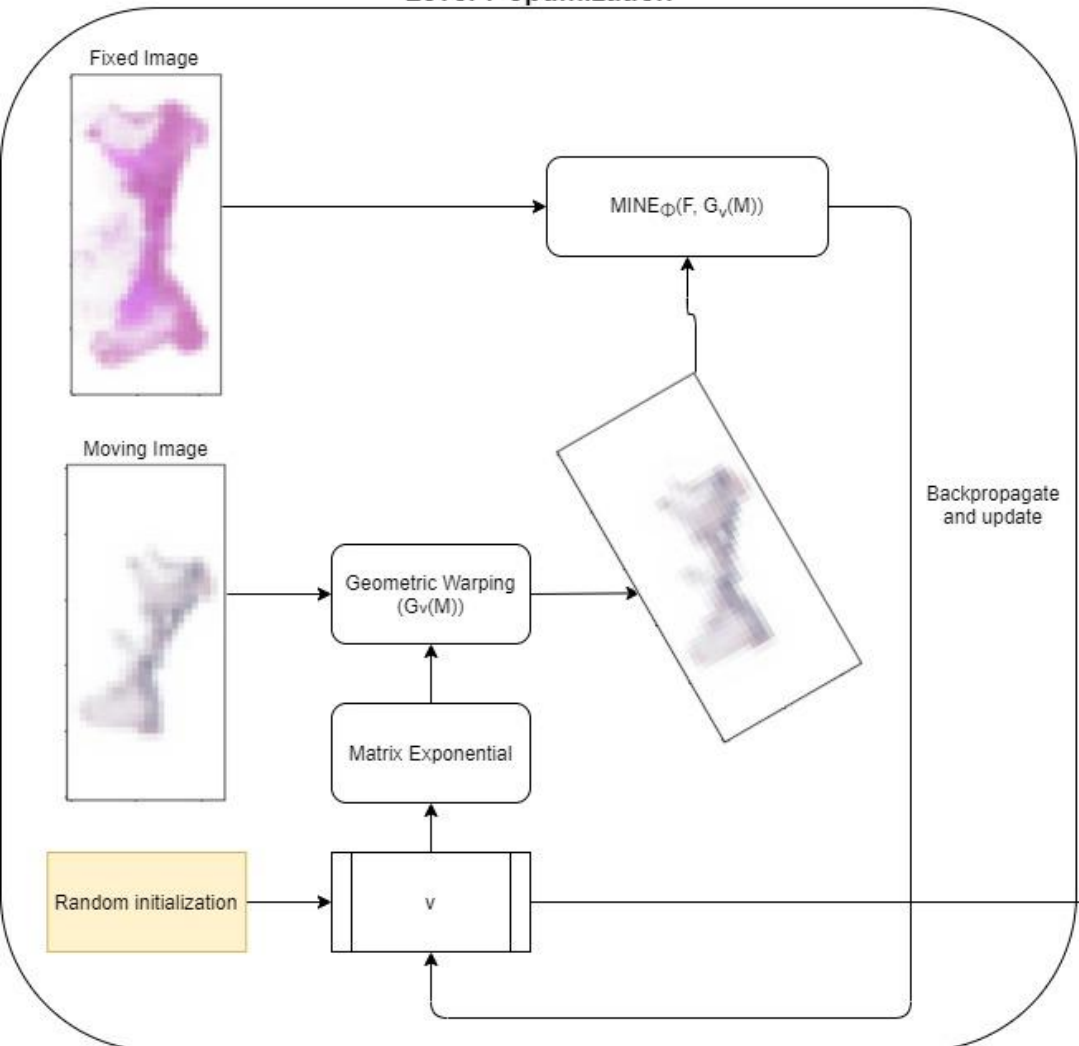
- Gaussian Pyramids

Image resolution  
increases going from  
the top to the bottom  
of the pyramid



An example image pyramid  
Picture source: MICCAI 2010 tutorial

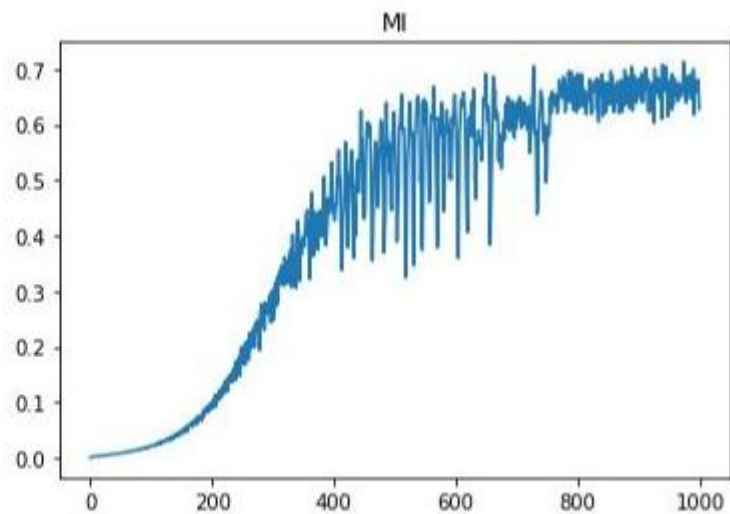
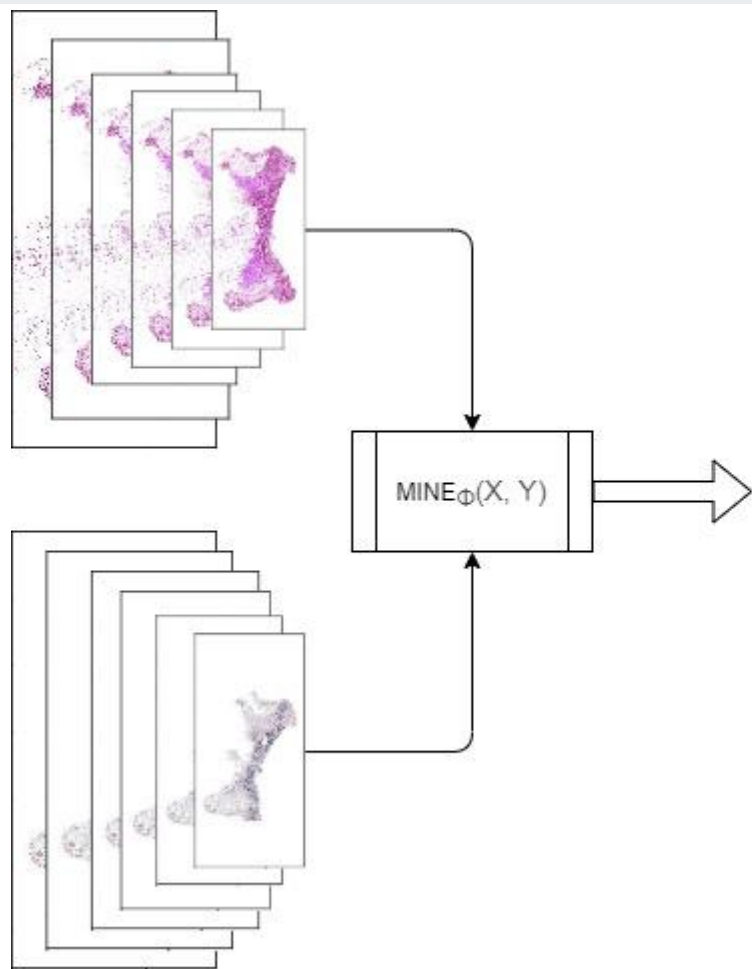
# Level 7 optimization







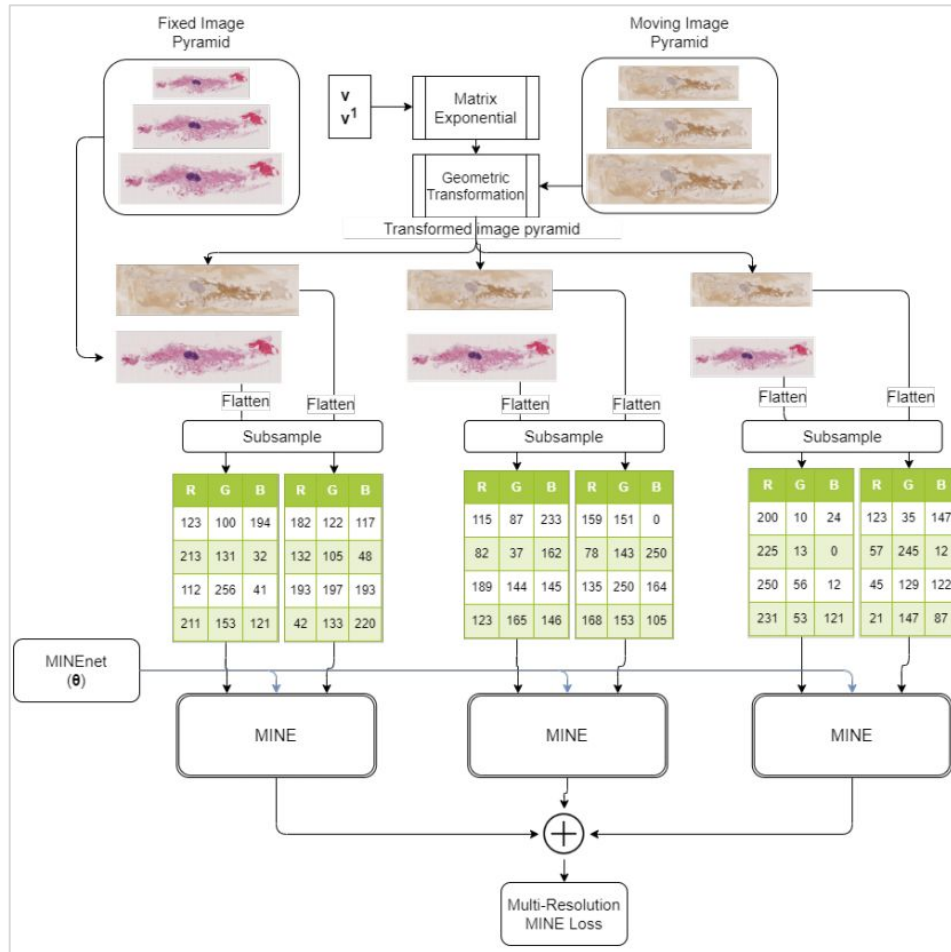
- Can we do better?
  - What if we did simultaneous optimization for all levels?
- Each level of optimization is for different images. So MI between them changes as well. Solution?
  - A single MINE can be trained for all of these!
- How?
  - Mini-batches can be constructed by sampling from all levels





# What about the loss?

- Since we are doing simultaneous optimization, with modern deep learning frameworks, it's very easy to combine the loss from each level and perform joint optimization.
- For eg, for just 1 level:
  - Loss =  $MI(F, G_v(M))$
- For 4 levels:
  - Loss =  $(\frac{1}{4}) * [MI(F_1, G_v(M_1)) + MI(F_2, G_v(M_2)) + MI(F_3, G_v(M_3)) + MI(F_4, G_v(M_4))]$





# Evaluation

- Public datasets
- Available ground truth



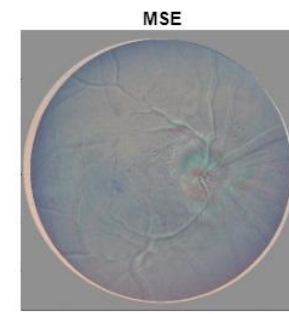
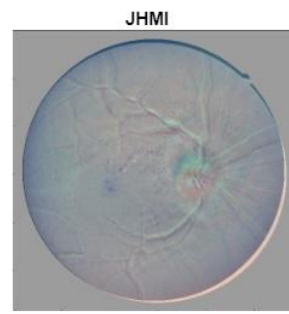
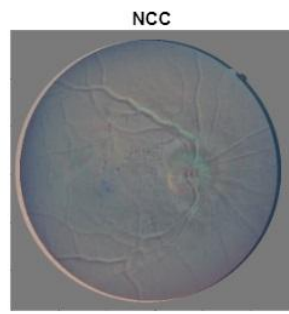
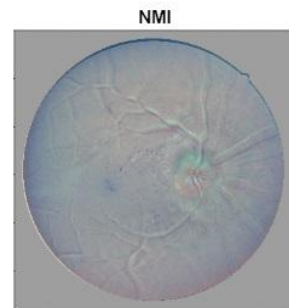
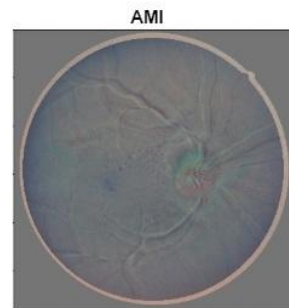
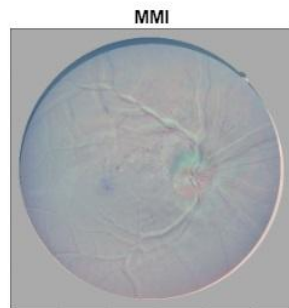
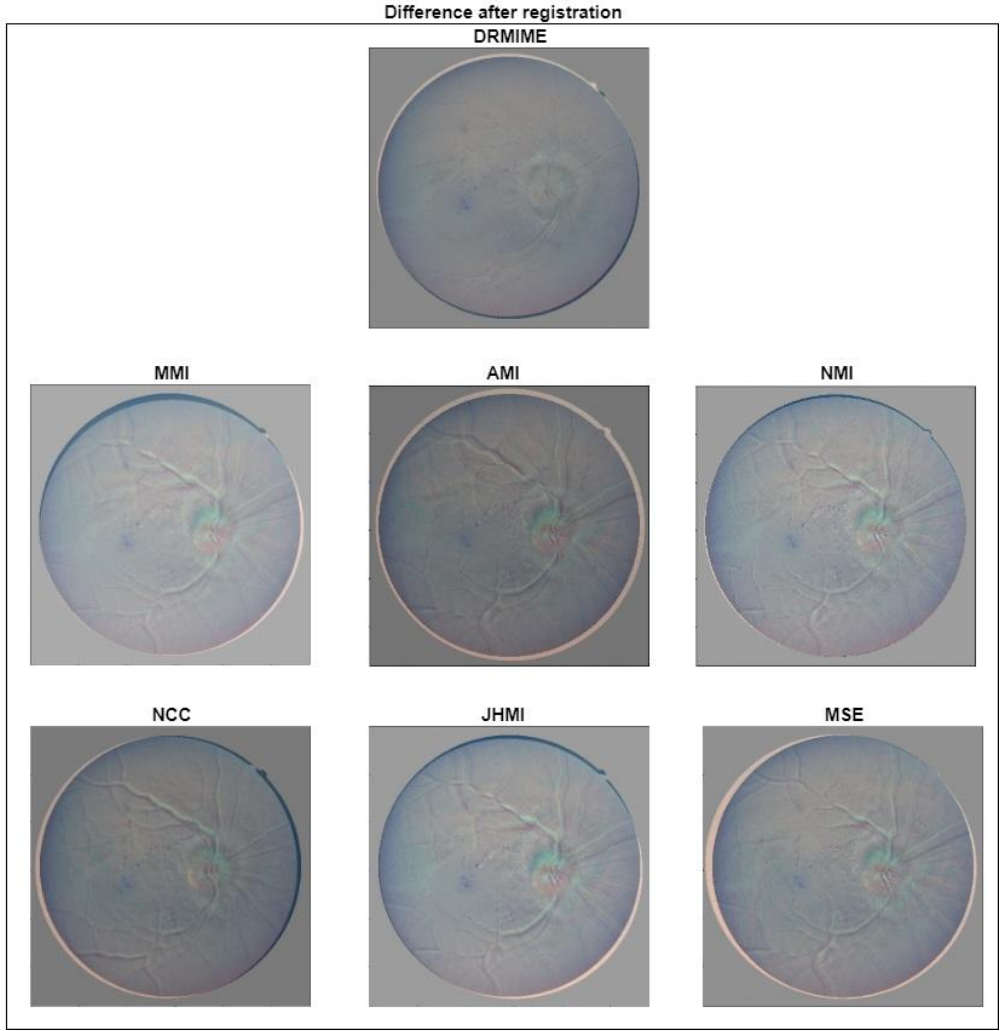
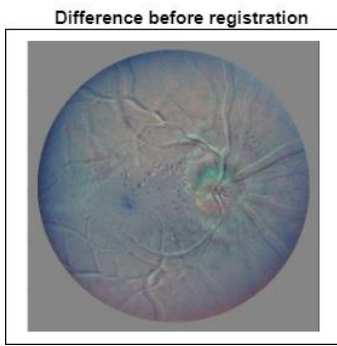
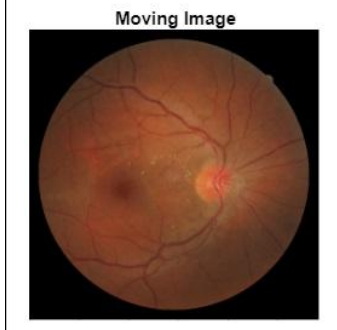
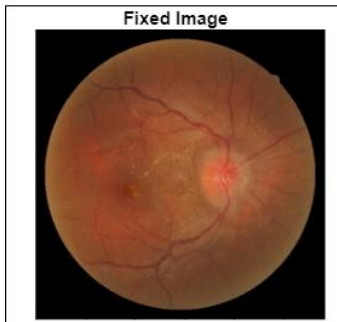
# Results

TABLE I: NAED for FIRE dataset along with paired t-test significance values

Algorithm	NAED (Mean $\pm$ STD)	p-value
DRMIME	<b>0.0048</b> $\pm$ 0.014	-
NCC	0.0194 $\pm$ 0.033	1.3e-04
MMI	0.0198 $\pm$ 0.034	5.4e-05
NMI	0.0228 $\pm$ 0.032	1.7e-08
JHMI	0.0311 $\pm$ 0.046	4.5e-07
AMI	0.0441 $\pm$ 0.028	1.4e-27
MSE	0.0641 $\pm$ 0.094	3.5e-03

TABLE II: NAED for ANHIR dataset along with paired t-test significance values

Algorithm	NAED (Mean $\pm$ STD)	p-value
DRMIME	<b>0.0384</b> $\pm$ 0.087	-
NCC	0.0461 $\pm$ 0.084	7.0e-04
MMI	0.0490 $\pm$ 0.082	6.2e-05
MSE	0.0641 $\pm$ 0.094	5.5e-14
NMI	0.0765 $\pm$ 0.090	3.0e-31
AMI	0.0769 $\pm$ 0.090	3.7e-30
JHMI	0.0827 $\pm$ 0.100	8.3e-21



Thank you!